SYSMAC CS-series MECHATROLINK-II-compatible Position Control Units CS1W-NCD71

Decrease TCO with Simple Operation, Reduced Wiring, Batch Settings, and Batch Management

- Control Servos for up to 16 axes in a motion network with one Position Control Unit that supports MECHATROLINK-II *
- * MECHATROLINK-II is a registered trademark of the MECHATROLINK Members Association.



CS1W-NCF71

Features

• Even Smaller

Positioning of up to 16 axes can be controlled with a body the size of one CS-series Unit. The compact body provides a perfect fit to meet the need for downsizing of equipment for multi-axis control.

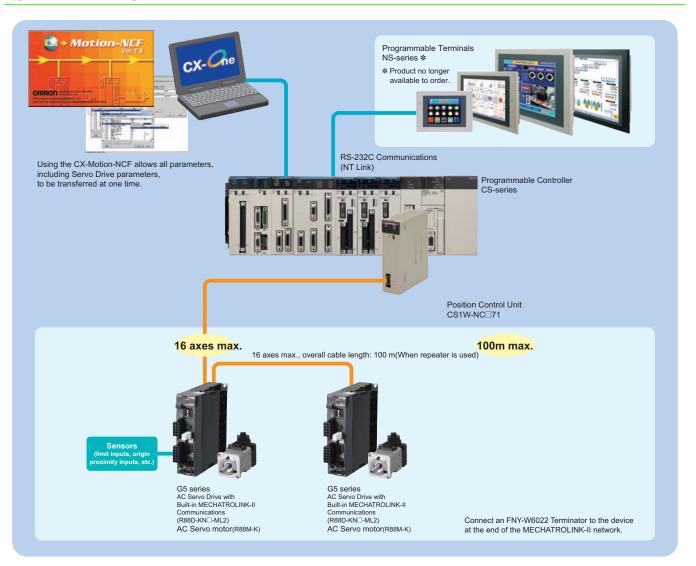
- Single-cable Connection with Flexible Wiring Placement With MECHATROLINK-II, connecting to the Servo Drive is easy. Just use a single cable (2-core shielded twisted-pair cable). Reduced wiring, with a total cable length of 50 m (or 30 m for 16 axes), allows more freedom in constructing systems.
- Less Time Spent on Startup and Maintenance Servo parameters can be set from the PLC.
 This means that settings and adjustments can be performed from one location rather than having to connect to each Servo Drive separately.

Simple Expansion

An easily expandable system can be constructed that is just as efficient now with a few axes or later with up to 16 axes.

• Linked Operation of Multiple Axes with MA Functionality The addition of an Interpolation Compensation Axis Stop Mode Setting and Interaxial Allowance Deviation Setting to linear interpolation compensation enables easier setting of linked operation between axes.

System Configuration



Ordering Information

International Standards

- The standards are abbreviated as follows: U: UL, U1: UL(Class I Division 2 Products for Hazardous Locations), C: CSA, UC: cULus, UC1: cULus (Class I Division 2 Products for Hazardous Locations), CU: cUL, N: NK, L: Lloyd, and CE: EC Directives.
- Contact your OMRON representative for further details and applicable conditions for these standards.

CS-series Units

Unit type	Product name	Specifications		No. of unit numbers	Current consumption (A)		Model	Standards
		Control output interface	No. of axes	allocated	5 V	26 V		
	MECHA- TROLINK-II- compatible Position	Control commands executed by	2		0.36		CS1W-NC271	
CS1 CPU Bus Units	Control Units	MECHATROLINK-II synchronous communications. Direct operation by ladder programming. Control mode: Position control, speed control,	4	1		-	CS1W-NC471	UC1, CE
		or torque control	16				CS1W-NCF71	

Support Software

Product name	Specifications	Number of licenses	Media	Model	Standards
FA Integrated Tool Package CX-One Ver. 4.□	The CX-One is a comprehensive software package that integrates Support Software for OMRON PLCs and components.	1 license *	DVD	CXONE-AL01D-V4	-
	CX-One Ver. 4.□ includes CX-Motion-NCF Ver. 1.□.				

Note: For details, refer to the CX-One Catalog (Cat. No. R134), visit your local OMRON website. * Multi licenses (3, 10, 30, or 50 licenses) and DVD media without licenses are also available for the CX-One.

MECHATROLINK-related Devices and Cables (Manufactured by Yaskawa Corporation)

Name		OMRON model number	Yaskawa model number
	0.5 m	FNY-W6003-A5	JEPMC-W6003-A5
	1.0 m	FNY-W6003-01	JEPMC-W6003-01
	3.0 m	FNY-W6003-03	JEPMC-W6003-03
MECHATROLINK-II Cables (with ring core and USB connector on both ends)	5.0 m	FNY-W6003-05	JEPMC-W6003-05
	10.0 m	FNY-W6003-10	JEPMC-W6003-10
	20.0 m	FNY-W6003-20	JEPMC-W6003-20
	30.0 m	FNY-W6003-30	JEPMC-W6003-30
MECHATROLINK-II Terminating Resistor	Terminating resistance	FNY-W6022	JEPMC-W6022
MECHATROLINK-II Repeater	Communications Repeater		JEPMC-REP2000-E

Note: MECHATROLINK-related Devices and Cables are manufactured by Yaskawa Corporation, but they can be ordered directly from OMRON using the OMRON model numbers. (Yaskawa-brand products will be delivered even when they are ordered from OMRON.)

Accessories

None

Mountable Racks

	CS1 system			CS1D system		
Model	CPU Rack	Expansion Backplane	Long-distance Expansion Rack	CPU Rack	Expansion Backplane	
CS1W-NCD71	16 Units max. (per CPU Unit)			16 Units max (pe	er CPU Unit)	

Specifications

General Specifications

Item	Specifications
Model	CS1W-NC271/471/F71
Internal current consumption	360 mA max. at 5 V DC
Dimensions	$130 \times 35 \times 101 \text{ mm} (W \times H \times D)$
Weight	188 g max.
Ambient operating temperature	0 to 55°C
Approved standards	CE, cULus, and C-tick
<u> </u>	

Specifications not listed above conform to general CS Series specifications.

Functions and Specifications

Item		Specifications					
Unit classification		CPU Bus Unit					
Applicable PLCs		CS Series					
Possible unit numb	per settings	0 to F					
	Common Operating Memory Area	Words allocated in CPU Bus Unit Area: 25 words (15 output words, 10 input words)					
I/O allocations	Axis Operating Memory Area	Allocated in one of the following areas (user-specified): CIO, Work, Auxiliary, Holding, DM, or EM Area.					
		Number of words allocated: 50 words (25 output words, 25 input words) × Highest axis No. used					
Compatible device	S	OMRON G5-series Servo Drives (Built-in MECHATROLINK-II communications) OMRON G-series Servo Drives (Built-in MECHATROLINK-II communications)					
Control method		Control commands executed using MECHATROLINK-II synchronous communications.					
Maximum number	of controlled axes	CS1W-NC271: 2 axes, CS1W-NC471: 4 axes, CS1W-NCF71: 16 axes					
	Position command unit	Command unit: Depends on the Electronic Gear Setting in the Servo Parameters. Default setting: Pulses					
	Speed command unit for posi- tion control	Command units/s					
Control units	Acceleration/deceleration speeds for position control	10,000 command units/s ²					
	Speed command unit for speed control	0.001% of the motor's momentary maximum rotation speed					
	Torque command unit for torque control	0.001% of the motor's momentary maximum torque					
	Position command range	-2,147,483,648 to 2,147,483,647 (command units)					
	Speed command range for posi- tion control	0 to 2,147,483,647 (command units/s)					
Control command range	Acceleration/deceleration speeds for position control	1 to 65,535 (10,000 command units/s²)					
	Speed command range for speed control	-199.999% to 199.999% The upper limit of the speed command range depends on the specifications of the Servo Drive.					
	Torque command range for torque control	-199.999% to 199.999% The upper limit of the torque command range depends on the specifications of the Servo Drive.					
	Servo lock/unlock	Creates (Servo lock) or releases (Servo unlock) the position loop on the PCU.					
	Position control	Positions to an absolute position or relative position according to the target position and target speed specified from the ladder program.					
	Origin determination	 Origin search: Establishes the origin using the specified search method. Present position preset: Changes the present position to a specified position to establish the origin. Origin return: Returns the axis from any position to the established origin. Absolute encoder origin: Establishes the origin using a Servomotor that has an absolute encoder, without having to use an origin search. 					
Control functions	Jogging	Outputs pulses at a fixed speed in the forward rotation or reverse rotation direction.					
	Interrupt feeding	Performs positioning by moving the axis a fixed amount when an external interrupt input is received while the axis is moving.					
	Speed control	Performs speed control by sending a command to the Servo Drive speed loop.					
	Torque control	Performs torque control by sending a command to the Servo Drive current loop.					
	Stop functions	 Deceleration stop: Decelerates the moving axis to a stop. Emergency stop: Positions the moving axis for the number of pulses remaining in the deviation counter and then stops the axis. 					

	Item	Specifications
	Acceleration/deceleration curves	Sets one of the following: a trapezoidal (linear) curve, an exponential curve, or an S-curve (moving average).
	Torque limit	Restricts the output torque during axis operation.
	Override	Multiplies the axis command speed by a specified ratio. Override: 0.01% to 327.67%
Auxiliary func- tions	Servo parameter transfer	Reads and writes the Servo Drive parameters from the ladder program in the CPU Unit.
tions	Monitoring function	Monitors the control status of the Servo Drive, such as the command coordinate positions, feedback posi- tion, current speed, and torque.
	Software limits	Limits software operation within the positioning range during position control.
	Backlash compensation	Compensates for the amount of play in the mechanical system according to a set value.
	Deviation counter reset	The position deviation in the Servo Drive's deviation counter can be reset to 0 (unit version 1.3 or later).
	Position Control Unit	One MECHATROLINK-II interface port
External I/O	Servo Drive I/O	Forward/reverse rotation limit inputs, origin proximity inputs, external interrupt inputs 1 to 3 (can be used as external origin inputs)
Self-diagnostic functions		Watchdog, flash memory check, memory corruption check
Error detection functions		Overtravel, Servo Drive alarm detection, CPU error, MECHATROLINK communications error, Unit setting error

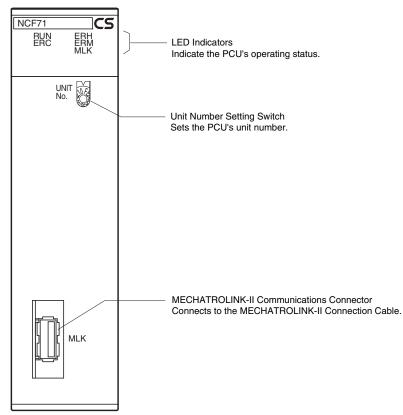
MECHATROLINK Specifications

Item	Specifications
Communications protocol	MECHATROLINK-II
Baud rate	10 Mbps
Maximum transmission distance	50 m *1
Minimum distance between stations	0.5 m
Transmission media	Shielded, twisted-pair cables
Maximum No. of stations	30 slave stations max. *2
Topology	Bus
Transfer cycle	250 μs to 8 ms
Communications method	Master-slave, totally synchronous
Encoding	Manchester encoding
Data length	17 bytes/32 bytes selectable *3

*1. This distance is the total length of the cable connected between devices. However, the maximum length depends on the number of devices connected and whether Repeaters are used.
*2. Up to 16 devices can be connected to the CS1W-NCF71, up to 2 devices can be connected to the CS1W-NC271, and up to 4 devices can be connected to the CS1W-NC471.
*3. The PCU data length is fixed at 32 bytes.

External Interface

CS1W-NC□71



LED Indicators

LED	Name	Color	Status	Details
RUN	Run	Green	Lit	The PCU is operating normally.
RUN	Run	Green	Not lit	Other condition
			Lit	A fatal error has occurred in the PCU and operation cannot continue.
ERC	Unit Error	Red	Flashing	A non-fatal error has occurred in the PCU and operation can continue.
			Not lit	Other condition
ERH	CPU Unit Error	Red	Lit	An error has occurred in the PLC.
ERN	CPU UNIL EITOI	Rea	Not lit	Other condition
			Lit	An error has occurred in MECHATROLINK communications.
ERM	MECHATROLINK Device Error	Red	Flashing	An error has occurred in a connected MECHATROLINK device.
			Not lit	Other condition
MLK	MECHATROLINK	Yellow	Lit	MECHATROLINK communications in progress
	Communications Status	reliow	Not lit	MECHATROLINK communications stopped

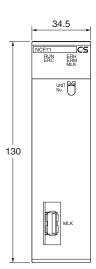
Functions Supported According to Position Control Unit Versions

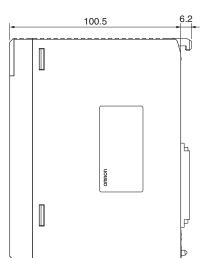
Madal	CS1W-NC□71						
Model	Unit Ver. 1.0	Unit Ver. 1.1	Unit Ver. 1.2	Unit Ver. 1.3	Unit Ver. 2.0	Unit Ver. 2.1	
Linear interpolation		Supported.	Supported.	Supported.	Supported.	Supported.	
Absolute encoder setup function	-		Supported.	Supported.	Supported.	Supported.	
Deviation counter reset	-			Supported.	Supported.	Supported.	
Establishing connections even when there are uncon- nected axes or axes with alarms that cannot be cleared	-	-	-	Supported.	Supported.	Supported.	
Transferring servo parameters even when there is an axis error	-	-	-	Supported.	Supported.	Supported.	
Creating servo locks during software limit detection when an absolute encoder is used		-	-	Supported.	Supported.	Supported.	
Driver main circuit OFF error detection only when the servo is locked	-	-	-	Supported.	Supported.	Supported.	
Using Holding Area address H512 and onwards for function block address allocations		-	-	Supported.	Supported.	Supported.	
Addition of rejoin function	-			-	Supported.	Supported.	
Eliminating connection restriction when Servo Drive alarms occur (enabling connection when alarm A.C90 occurs)		-	-	-	Supported.	Supported.	
Addition of origin search operation modes	-	-	-	-	Supported.	Supported.	
Addition of origin search preset function	-	-	-	-	Supported.	Supported.	
Faster setting for transfer cycle and communications cycle when setting the absolute encoder PG zero point position offset with an origin search	-	-	-	-	-	Supported.	

Dimensions

CS1W-NC271 CS1W-NC471 CS1W-NCF71







(Unit: mm)

Related Manuals

English Cat. No.	Japanese Cat. No.	Model	Name
W426	SBCE-323	CS1W-NC□71/ CJ1W-NC□71 (-MA)	CS1W/CJ1W-NCD71 (-MA) CS/CJ-series MECHATROLINK-II-compatible Postion Controll Unit User's Manual
W436	SBCE-328	CXONE-ALDD-VD	CX-Motion-NCF Operation Manual
-	SBCE-055	CS1W-NCF71/CJ1W-NCF71	CS1W-NCF71/CJ1W-NCF71 Position Controll Unit (ONNUC G-series) Technical Guide

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