# **E6B2-C**

CSM\_E6B2-C\_DS\_E\_6\_3

# **General-purpose Encoder with External Diameter of 40 mm**

- · Incremental model
- External diameter of 40 mm.
- Resolution of up to 2,000 ppr.



Be sure to read Safety Precautions on

For the most recent information on models that have been certified for safety standards, refer to your OMRON website.

#### **Ordering Information**

#### Encoders [Refer to Dimensions on page 5.]

Power supply voltage	Output configura- tion	Resolution (pulses/rotation)	Model	
5 to 24 VDC	NPN open-collector output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	E6B2-CWZ6C (resolution) 0.5M Example: E6B2-CWZ6C 10P/R 0.5M	
		720, 800, 1,000, 1,024		
		1,200, 1,500, 1,800, 2,000		
12 to 24 VDC	PNP open-collector output	100, 200, 360, 500, 600	<b>E6B2-CWZ5B (resolution) 0.5M</b> Example: E6B2-CWZ5B 100P/R 0.5M	
		1,000		
		2,000		
5 to 12 VDC	Voltage output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600		
		1,000	E6B2-CWZ3E (resolution) 0.5M Example: E6B2-CWZ3E 10P/R 0.5M	
		1,200, 1,500, 1,800, 2,000	- Example: Lob2-GVVZ3E TOF/R 0.3W	
5 VDC	Line-driver output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600		
		1,000, 1,024	E6B2-CWZ1X (resolution) 0.5M Example: E6B2-CWZ1X 10P/R 0.5M	
		1,200, 1,500, 1,800, 2,000	Example: Lobe-Ovv21X 101 /K 0.5W	

#### Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks	
	E69-C06B	Provided with the product.	
Couplings	E69-C68B	Different end diameter	
Couplings	E69-C610B	Different end diameter	
	E69-C06M	Metal construction	
Flanges	E69-FBA		
rianges	E69-FBA02	E69-2 Servo Mounting Bracket provided.	
Servo Mounting Bracket	E69-2		

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Note: 1. Refer to Rotary Encoders Accessories on your OMRON website for details.

2. Refer to Precautions For Correct Use of Rotary Encoders on your OMRON website when using the Rotary Encoders together with a Coupling.

## **Ratings and Specifications**

Item	Model	E6B2-CWZ6C	E6B2-CWZ5B	E6B2-CWZ3E	E6B2-CWZ1X			
Power supply voltage		5 VDC –5% to 24 VDC +15%, ripple (p-p): 5% max.	12 VDC –10% to 24 VDC +15%, ripple (p-p): 5% max.	5 VDC –5% to 12 VDC +10%, ripple (p-p): 5% max.	5 VDC ±5%, ripple (p-p): 5% max.			
Current consumption *1		0.6 W max. (80 mA max.)	0.8 W max. (100 mA max.)	0.6 W max. (100 mA max.)	160 mA max.			
Resolution (pulses/rotation)		10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000	100, 200, 360, 500, 600, 1,000, 2,000	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 1,000, 1,200, 1,500, 1,800, 2,000	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000			
Output phases		Phases A, B, and Z	Phases A, $\overline{A}$ , B, $\overline{B}$ , Z, and $\overline{Z}$					
Phase difference between outputs		$90^{\circ}\pm45^{\circ}$ between A and B (1/4 T $\pm$ 1/8 T)						
Output configuration		NPN open-collector output	PNP open-collector output	Voltage output (NPN output)	Line driver output *2			
Output capacity		Applied voltage: 30 VDC max. Sink current: 35 mA max. Residual voltage: 0.4 V max. (at sink current of 35 mA)	Applied voltage: 30 VDC max. Source current: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA)	Output resistance: $2 \text{ k}\Omega$ Sink current: $20 \text{ mA max}$ . Residual voltage: $0.4 \text{ V max}$ . (at sink current of $20 \text{ mA}$ )	AM26LS31 equivalent Output current High level: Io = -20 mA Low level: Is = 20 mA Output voltage: Vo = 2.5 V min. Vs = 0.5 V max.			
Maximum response frequency *3		100 kHz	50 kHz	100 kHz	0 kHz			
Rise and fall times of output		1 μs max. (Control output voltage: 5 V, Load resistance: 1 k $\Omega$ , Cable length: 2 m max.)	1 μs max. (Cable length: 2 m max., Sink current: 10 mA)		0.1 μs max. (Cable length: 2 m max., Io = –20 mA, Is = 20 mA)			
Starting torque		0.98 mN·m max.						
Moment of inertia		$1 \times 10^{-6} \text{ kg} \cdot \text{m}^2 \text{ max.}; 3 \times 10^{-7} \text{ kg} \cdot \text{m}^2 \text{ max. at } 600 \text{ P/R max.}$						
Shaft	Radial	30 N						
load- ing	Thrust	20 N						
Maximum permissible speed		6,000 r/min						
Protection circuits		Power supply reverse polarity protection, Load short-circuit protection						
Ambient temperature range		Operating: -10 to 70°C (with no icing), Storage: -25 to 85°C (with no icing)						
Ambient humidity range		Operating/Storage: 35% to 85% (with no condensation)						
Insulation resistance		20 M $\Omega$ min. (at 500 VDC) between current-carrying parts and case						
Dielectric strength		500 VAC, 50/60 Hz for 1 min between current-carrying parts and case						
Vibration resistance		Destruction: 10 to 500 Hz, 150 m/s² or 2-mm double amplitude for 11 min 3 times each in X, Y, and Z directions						
Shock r	Destruction: 1,000m/s² 3 times each in X, Y, and Z directions							
Degree protecti		IEC 60529 IP50						
Connection method		Pre-wired Models (Standard cable length: 500 mm)						
Materials		Case: ABS, Main unit: Aluminum, Shaft: SUS420J2						
Weight (packed state)		Approx. 100 g						
Accessories Coupling, Hexagonal wrench, Instruction manual								
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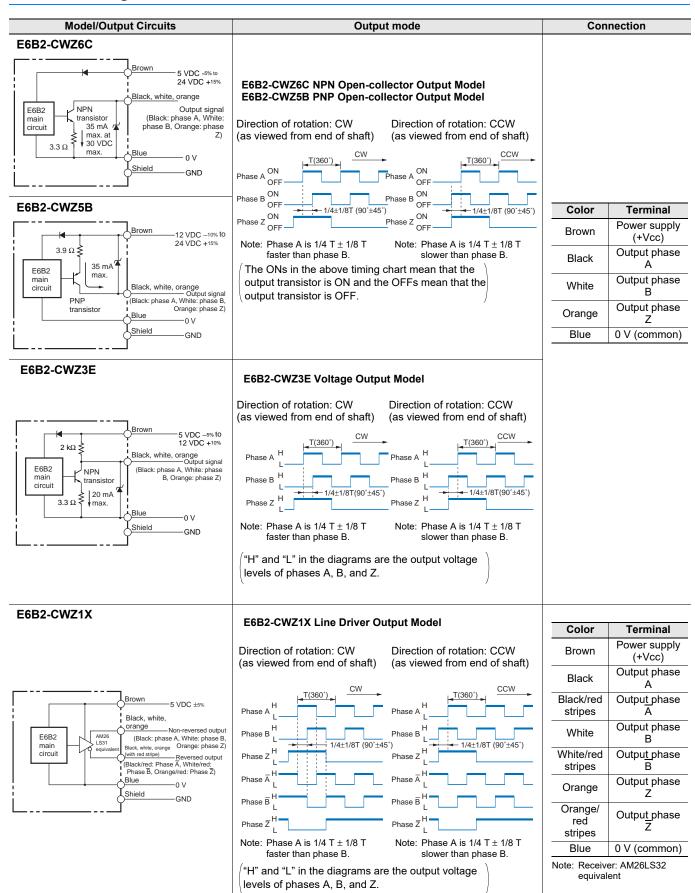
Maximum electrical response speed (rpm) =  $\frac{\text{Maximum response frequency}}{\text{Posolution}} \times 60$ Resolution

This means that the E6B2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.

<sup>\*1.</sup> An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.
\*2. The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable. The quality is equivalent to AM26LS31.

<sup>\*3.</sup> The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

#### I/O Circuit Diagrams



Note: 1. The shielded cable outer core (shield) is not connected to the inner area or to the case.

- 2. The phase A, phase B, and phase Z circuits are all identical.
- 3. Normally, connect GND to 0 V or to an external ground.

### **Safety Precautions**

Be sure to read the precautions for all models in the website at: http://www.ia.omron.com/.

#### **MARNING**

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



#### **Precautions for Safe Use**

- Do not use the product in excess of the rated voltage. Applying voltages beyond the rated voltage range may cause the product to break or burn.
- Avoid wiring the product's cables parallel to power lines or high voltage lines. Doing so may cause the product to malfunction due to induction or may cause the damage the product.
- If surge occurs in the power supply, connect a surge absorber between the power supply terminals to absorb the surge. Minimize the wiring length to prevent the product from being affected by noise, etc.
- 4. Since improper pulses may occur when the power is turned on or off, use the devices connected to this product at least 0.1 seconds before or after the power is turned on or off.
- Be careful when wiring, such as being careful with the polarities of the power supply. Incorrect wiring may break or burn the product.
- 6. Do not short-circuit the load. Doing so may break or burn the product. In case of load short-circuit (except E6B2-CWZ1X), the product will shut down the output. At that time, please solve the short-circuit and restart the power.
- Do not use the encoder under the environment with explosive or ignition gas.
- 8. Never disassemble, repair nor tamper with the product.

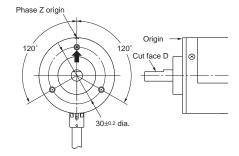
#### **Precautions for Correct Use**

- Since the product consists of high-precision components, handle it with utmost care.
- 2. Be careful not to expose the product to water or oil.
- Be sure to turn off the power supply before wiring. If the output line contacts the power supply line while the power is being supplied, the output circuit may be damaged.
- 4. If the product is mounted and wired with a cord, do not pull the cord with force greater than 29.4 N.
- 5. Be careful not to apply excessive load to the shaft. Excessive load may cause the product break. Especially when linking with a chain, timing belt, or gears, connect a separate bearing before the coupling to the product.
- 6. If an installation error such as misalignment is too large, (in case using the coupling or without coupling) the shaft will be subjected to an excessive load which will damage it or shorten its service life. Be careful when installing.
- 7. When inserting the shaft in the coupling, do not use excessive force (by striking it with hammer, for example).
- 8. When installing or removing the coupling, do not apply an excessive being, compressing, or tensile force.

#### Mounting

Origin Indication

It is easy to adjust the position of phase Z with the origin indication function. The following illustration shows the relationship between phase Z and the origin. Set cut face D to the phase Z origin as shown in the illustration.



 Do not extend the length of the cable to more than 2 m. If the cable must be more than 2 m, use a Model with a Line-driver Output (max. length: 100 m).

#### Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

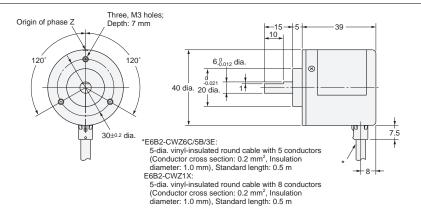
Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

#### **Dimensions**

#### **Encoder**







#### **Accessories (Order Separately)**

Couplings Flanges Servo Mounting Bracket

E69-C06B E69-FBA E69-2

E69-C68B E69-FBA02

E69-C610B E69-C06M

Refer to Rotary Encoders Accessories on your OMRON website for details.

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