

Application example

1. Enable Operation: Makes a Servo Drive ready to operate.

[ENG]Enable Operation: Makes a Servo Drive ready to operate.
 [JPN]運転準備：サーボドライバを運転可能状態に切り替えます。

Variable: Execute_Ready
 [ENG]The Servo Drive becomes ready to operate when the value of this variable changes to TRUE. The ready state is reset when the variable changes to FALSE.
 [JPN]TRUEになると運転可能状態となり、FALSEになると運転可能状態を解除します。

2. Home: Operates the motor to determine home.

[ENG]Home: Operates the motor to determine home.
 [JPN]原点復帰：機械原点をセットします。

Variable: Execute_Home
 [ENG]The MC_Home instruction is executed when the value of this variable changes to TRUE.
 [JPN]立ち上がり時に原点復帰命令を開始します。

3. Manual Operation: Jogs an axis according to the specified target velocity.

[ENG]Manual Operation: Jogs an axis according to the specified target velocity.
 [JPN]手動運転：指定した目標速度にしたがって、ジョグを行います。

Variable: X_Jog_Pos/ X_Jog_Nega
 [ENG]When the value of this variable changes to TRUE, the Axis X starts moving in the positive/negative direction. When it changes to FALSE, the Axis X stops moving.
 [JPN]TRUEになると軸が正方向/負方向へ移動を開始します、FALSEになると移動を終了します。

Variable: Y_Jog_Pos/ Y_Jog_Nega
 [ENG]When the value of this variable changes to TRUE, the Axis Y starts moving in the positive/negative direction. When it changes to FALSE, the Axis Y stops moving.
 [JPN]TRUEになると軸が正方向/負方向へ移動を開始します、FALSEになると移動を終了します。

Variable: R_Jog_Pos/ R_Jog_Nega
 [ENG]When the value of this variable changes to TRUE, the Axis R(Theta) starts moving in the positive/negative direction. When it changes to FALSE, the Axis R(Theta) stops moving.
 [JPN]TRUEになると軸が正方向/負方向へ移動を開始します、FALSEになると移動を終了します。

4. Demonstration: Performs demonstration.

[ENG]Demonstration: Performs demonstration.
 [JPN]手動動作：手動動作を実行します。

Variable: Execute_Demo
 [ENG]A demonstration is performed when the value of this variable changes to TRUE.
 [JPN]立ち上がり時に手動動作を開始します。

(Additional information)

To confirm 3D operation, select **3D Visualizer** from the View menu. You can confirm the operation on the 3D Visualizer.

Related manuals

Sysmac Studio Version 1 Operation Manual (W504-E1)
 Sysmac Studio 3D Simulation Function Operation Manual (W618-E1)

■ Variable Tables

Input Variables

Meaning	Name	Data type	Default	Range	Description
Enable Operation	Execute_Ready	BOOL		TRUE or FALSE	The Servo Drive becomes ready to operate when the value of this variable changes to TRUE. The ready state is reset when the variable changes to FALSE.
Home	Execute_Home	BOOL		TRUE or FALSE	The MC_Home instruction is executed when the value of this variable changes to TRUE.
Jog Axis X in Positive Direction	X_Jog_Pos	BOOL		TRUE or FALSE	When the value of this variable changes to TRUE, the Axis X starts moving in the positive direction. When it changes to FALSE, the Axis X stops moving.
Jog Axis X in Negative Direction	X_Jog_Nega	BOOL		TRUE or FALSE	When the value of this variable changes to TRUE, the Axis X starts moving in the negative direction. When it changes to FALSE, the Axis X stops moving.
Jog Axis Y in Positive Direction	Y_Jog_Pos	BOOL		TRUE or FALSE	When the value of this variable changes to TRUE, the Axis Y starts moving in the positive direction. When it changes to FALSE, the Axis Y stops moving.
Jog Axis Y in Negative Direction	Y_Jog_Nega	BOOL		TRUE or FALSE	When the value of this variable changes to TRUE, the Axis Y starts moving in the negative direction. When it changes to FALSE, the Axis Y stops moving.
Jog Axis R(Theta) in Positive Direction	R_Jog_Pos	BOOL		TRUE or FALSE	When the value of this variable changes to TRUE, the Axis R(Theta) starts moving in the positive direction. When it changes to FALSE, the Axis R(Theta) stops moving.
Jog Axis R(Theta) in Negative Direction	R_Jog_Nega	BOOL		TRUE or FALSE	When the value of this variable changes to TRUE, the Axis R(Theta) starts moving in the negative direction. When it changes to FALSE, the Axis R(Theta) stops moving.
Demonstration	Execute_Demo	BOOL		TRUE or FALSE	A demonstration is performed when the value of this variable changes to TRUE.

Output Variables

Meaning	Name	Data type	Range	Description

■ Version History

Version	Date	Contents
1.00	July 2020	Original production.

■ Note

This document explains the function of the sample programs specifically prepared for 3D simulation.

It does not provide information of restrictions on the use of Units and Components or combination of them. For actual applications, make sure to read the operation manuals of the applicable product

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